NEETHU RENJITH

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EXPERIENCE

Gridspace Inc. Machine learning software engineer

🛗 23 July 2020 - Now

CA. USA

- Currently in charge of developing high level functionalities for our Spoken Dialogue System Authoring Language. I own this project endto-end from identifying common customer use cases, to validating, implementing, and testing each functionality to facilitating user adoption.
- Improved performance of **Automatic Speech Recognition System** by designing and implementing taggers and parsers for several types of data. They are being used by our Spoken Dialogue System.
- Headed the development of the call flow manager, one of the four main verticals of our new flagship product. Owned 90% of the codebase and led the product planning from ideation to launch. Created a sophisticated web based application using React, capable of supporting billions of calls with a few seconds of compile time.
- Integrated core product access with third-party cloud communications platforms. Provides continued on-boarding and support for customers who access the product through these platforms.
- Developed Machine Learning algorithms to improve search quality of our Knowledge Base Software.
- Part of the product deployment team, in charge of managing releases and customer facing kubernetes realms.
- Mentored summer internships and conduct interviews for recruiting as a part of **the hiring team**.

Al for climate change with Prof. Andrew Ng Research assistant

15 July - 15 Dec, 2019

CA, USA

 Explored semi-supervised learning methods to handle large unlabeled datasets with minimal hand labeling. Achieved 250% higher accuracy compared to purely supervised methods by utilizing unlabeled data on benchmark datasets.

PROJECTS

CNNs for visual recognition Videos from image using GANs

- Created 3 second videos from a single frame using GANs and generative convolutional LSTMs trained on AWS.
- Stylized the videos using multi-style fast neural style transfer.

Machine learning Effectiveness of MOOC videos

- Used transcript level features to predict course engagement and model user behavior based on click-stream measures.
- This work has been presented at the BayLan 2019 conference

Robotic software Autonomous food delivery bot

- Programmed TurtleBot on a ROS platform to explore and map miniature city using EKF SLAM.
- Food items identified, during exploration, using pretrained neural net could then be collected efficiently as per user request.

% neethurenjith.com

www.github.com/Neethu-nr

EDUCATION

MS in Aero/Astro Stanford University

Sept 2018 - June 2020

B.Tech in Aerospace Engineering Indian Institute of Technology

may 2014 - May 2018

Minor: Industrial Engineering

Thesis: Coordinated guidance and control of two satellites for rendezvous and docking

ACHIEVEMENTS

- Paper presented at the BayLan 2019 conference: Predicting Clickstream Engagement in MOOCs
- Awarded KC Mahindra scholarship for graduate studies and Merit Cum Means for Undergraduate studies by the Central Govt. of India

TEACHING ASSISTANT

- Control design techniques with prof.Steve Rock (Fall, Winter 2019)
- Information retrieval and web search with prof. Chris Manning and prof.Pandu Nayak (Spring 2019)

SKILLS



DATABASES

SQL	PostgresQL	Cockroach
Redis	Elasticsearch	Prometheus